

---

# Nonparametric IV and Partial Identification

Andres Santos

University of California - San Diego

June 12, 2010

[a2santos@ucsd.edu](mailto:a2santos@ucsd.edu)

# Instrumental Variables

---

$$Y = \theta_0(X) + \epsilon ,$$

with  $E[\epsilon|X] \neq 0$ ,  $E[\epsilon|Z] = 0$  and  $\theta \in \Theta$  for some smooth set of functions  $\Theta$ .

Defining  $\Upsilon : L^2(X) \rightarrow L^2(Z)$  by  $\Upsilon(\theta) = E[\theta(X)|Z]$  we obtain the equation:

$$E[Y|Z] = \Upsilon(\theta) .$$

## Problem is ill posed if:

- $\Upsilon^{-1}$  exists but is not continuous (*instability*).
- $E[Y|Z]$  is not in the image of  $\Upsilon$  (*nonexistence*).
- $\Upsilon$  is not injective (*nonuniqueness*).

# Set of Solutions

---

Assuming existence and for  $\mathcal{N}(\Upsilon)$  the null space of  $\Upsilon$ , the set of solutions is:

$$\mathbf{V}_0 \equiv \theta_0 + \mathcal{N}(\Upsilon) .$$

**Note:** Identified set is an affine vector space, potentially infinite dimensional.

## Restrict domain of $\Upsilon$ to $\Theta$

- The relevant set of solutions becomes  $\mathbf{V}_0 \cap \Theta$ .
- Regularize through compactness of  $\Theta \Rightarrow$  nonuniqueness with stability.
- Inverse correspondence  $\Upsilon^{-1}$  is upper hemicontinuous.

# Parameter Space

**Norms**  $X \in \mathbf{R}^{d_x}$ ,  $m, m_0$  integers,  $\delta_0 > \delta > 0$  scalars with  $m_0 > \frac{d_x}{2}$  and  $\frac{d_x}{m} + \frac{d_x}{\delta} < 2$

$$\|\theta\|_s^2 \equiv \sum_{|\lambda| \leq m+m_0} \int [D^\lambda \theta(x)]^2 (1 + x'x)^{\delta_0} dx \qquad \|\theta\|_{c\delta} \equiv \max_{|\lambda| \leq m} \sup_x |D^\lambda \theta(x)| (1 + x'x)^{\frac{\delta}{2}}$$

**Vector Spaces** For  $\mathcal{X} \subseteq \mathbf{R}^{d_x}$  the support of  $X$  define the metric vector spaces:

$$W^s(\mathcal{X}) \equiv \{\theta : \mathcal{X} \rightarrow \mathbf{R} \text{ s.t. } \|\theta\|_s < \infty\} \qquad W^{c\delta}(\mathcal{X}) \equiv \{\theta : \mathcal{X} \rightarrow \mathbf{R} \text{ s.t. } \|\theta\|_{c\delta} < \infty\}$$

**Parameter Space**  $\Theta$  is the closure under  $\|\cdot\|_{c\delta}$  of a sphere in  $W^s(\mathcal{X})$ :

$$\Theta \equiv \text{cl}\{\theta \in W^s(\mathcal{X}) : \|\theta\|_s \leq B\} .$$

**Key:**  $\Theta$  is bounded in  $W^s(\mathcal{X})$  and compact in  $W^{c\delta}(\mathcal{X})$ .

# Identification

**Question:** Does restriction  $\theta_0 \in \Theta$  identify  $\theta_0$ ?

**Answer:** If  $\theta_0 \in W^s(\mathcal{X})$ , then unlikely **unless**  $\mathcal{N}(\Upsilon) \cap W^s(\mathcal{X}) = \emptyset$ , since:

$$\mathbf{V}_0 \cap \Theta \supseteq \underbrace{\{\theta_0 + \mathcal{N}(\Upsilon) \cap W^s(\mathcal{X})\}}_{\text{affine vector space}} \cap \underbrace{\{\theta \in W^s(\mathcal{X}) : \|\theta\|_s \leq B\}}_{\text{sphere}} .$$

## Three cases

- Sphere does not intersect affine space (*misspecification*)
- Sphere intersects affine space at many points (*partial identification*)
- Sphere is tangent to affine space (*identification*)

**Basic Insight:**  $\mathcal{N}(\Upsilon) \cap W^s(\mathcal{X}) \neq \emptyset$ , then identification fails for  $B$  large.

# Counterexamples

**Goal:** Find  $f_{X|Z}(x|z)$  such that  $\int \psi(x) f_{X|Z}(x|z) dx = 0$  for some  $\psi \in W^s(\mathcal{X})$ .

## Basic Approach:

- Suppose  $\{\psi_k(x)\}_{k=1}^{\infty}$  and  $\{\phi_j(z)\}_{j=1}^{\infty}$  are basis of  $L^2(X)$  and  $L^2(Z)$ .
- Let  $f_{X|Z}(x|z)$  be square integrable and admitting for an expansion (in  $\|\cdot\|_{L^2}$ )

$$f_{X|Z}(x|z) = \sum_{k=1}^{\infty} \sum_{j=1}^{\infty} a_{kj} \psi_k(x) \phi_j(z) .$$

- If for some  $k^*$  we have  $\psi_{k^*} \in W^s(\mathcal{X})$  and  $a_{k^*j} = 0$  for all  $j$  then:

$$\theta_0 + \psi_{k^*} \in \mathbf{V}_0 \cap W^s(\mathcal{X}) .$$

**But!** Most basis functions are in  $W^s(\mathcal{X})$  and it is easy to construct  $f_{X|Z}(x|z)$ .

# Counterexamples

**Example 1:** Suppose  $(X, Z) \in [-1, 1]^2$  and  $f_{X|Z}(x|z)$  is polynomial of finite order.

**Example 2:**  $(X, Z)$  scalars, correlation arbitrarily close to one, but not identified.

In many instances, the set of densities for which identification fails is dense.

$$\mathbf{D}(K) \equiv \{f : K \rightarrow \mathbf{R} : f \geq 0, \int_K f(x, z) dx dz = 1, f \text{ is continuous} \}.$$

Further define the subset of  $\mathbf{D}(K)$  for which identification fails by:

$$\mathbf{D}_\emptyset(K) \equiv \{f \in \mathbf{D}(K) : 0 \neq \theta \in W^s(\mathcal{X}), \text{ such that } \int_K \theta(x) f(x, z) dx = 0 \quad \forall z \}.$$

**Lemma** If  $K$  is compact, then  $\mathbf{D}_\emptyset(K)$  is dense in  $\mathbf{D}(K)$  under  $\|\cdot\|_\infty$ .

# Literature Review

---

**Nonparametric/Semiparametric IV:** Ai & Chen (2003), Darolles, Florens & Renault (2003), Newey & Powell (2003), Blundell, Chen & Kristensen (2004), Hall & Horowitz (2005), Horowitz (2006, 2007), Chen & Pouzo (2008, 2010).

**Causality/Triangular systems:** Newey, Powell & Vella (1999), Chesher (2003, 2005, 2007), Imbens & Newey (2006).

**Partial Identification:** Manski (2003), Chernozhukov, Hong & Tamer (2004), Severini & Tripathi (2006, 2007), Romano & Shaikh (2008, 2009), Chernozhukov, Lee & Rosen (2009).

**Specification Testing:** Anderson & Rubin (1949), Bierens (1990), Bierens & Ploberger (1997), Stinchcombe & White (1998).



# Talk Outline

---

1. Testing Framework.
2. Test Statistic and Asymptotic Distribution.
3. Almost Sure Consistent Bootstrap.
4. Monte Carlo Evidence.

Testing

Statistic

Bootstrap

Simulations

# Testing Framework

# Basic Setup

---

**Identified Set:** Models consistent with the exogeneity assumption on  $Z$

$$\Theta_0 \equiv \{\theta \in \Theta : E[Y - \theta(X)|Z] = 0\}$$

**Hypothesis Tests:** Does at least one element of  $\Theta_0$  satisfy a restriction  $R$ ?

$$H_0 : \Theta_0 \cap R \neq \emptyset \qquad H_1 : \Theta_0 \cap R = \emptyset$$

**Under Identification:** If  $\Theta_0$  is a singleton, so that  $\Theta_0 = \{\theta_0\}$ , then we have:

$$H_0 : \Theta_0 \cap R \neq \emptyset \Leftrightarrow \theta_0 \in R \qquad H_1 : \Theta_0 \cap R = \emptyset \Leftrightarrow \theta_0 \notin R$$

**Hence:** Under identification, analysis simplifies to inference on true parameter.

# The Set $R$

---

Functions in the set  $R$  are assumed to satisfy a linear equality restriction:

$$R \equiv \{ \theta \in W^{c\delta}(\mathcal{X}) : L(\theta) = l \}$$

**Assumption:**  $L : (W^{c\delta}(\mathcal{X}), \|\cdot\|_{c\delta}) \rightarrow (\mathcal{L}, \|\cdot\|_{\mathcal{L}})$  is linear, continuous operator.

## Comments

- Restriction of  $L$  linear compensated by flexibility in choosing  $(\mathcal{L}, \|\cdot\|_{\mathcal{L}})$ .
- Strength of norm  $\|\cdot\|_{c\delta}$  makes continuity easy to verify.
- Assumption can be relaxed to  $R$  closed subset of  $W^{c\delta}(\mathcal{X})$  ...  
... **but** inference becomes potentially conservative.

# Identifiable Functionals

Often we are interested in a functional  $f : \Theta \rightarrow \mathbf{R}^k$ , and the identified set:

$$\mathcal{F}_0 \equiv \{f(\theta) : \theta \in \Theta_0\} .$$

**Goal:** Construct a confidence region  $C_n(1 - \alpha)$  satisfying the requirement:

$$\inf_{\theta \in \Theta_0} \liminf_{n \rightarrow \infty} P(f(\theta) \in C_n(1 - \alpha)) \geq 1 - \alpha .$$

**Solution:** Proceed by test inversion of the family of null hypotheses:

$$H_0(\gamma) : \Theta_0 \cap R(\gamma) \neq \emptyset \quad R(\gamma) \equiv \{\theta \in W^{c\delta}(\mathcal{X}) : f(\theta) = \gamma\} .$$

**If** size can be controlled for each  $H_0(\gamma)$ , **then** coverage requirement is satisfied.

# Identifiable Functionals

**Example:** Suppose we want to know the value of  $\theta_0$  at a point  $x_0$ , then:

$$R(\gamma) = \{\theta \in W^{c\delta}(\mathcal{X}) : \theta(x_0) = \gamma\} .$$

Just let  $(\mathcal{L}, \|\cdot\|_{\mathcal{L}}) = (\mathbf{R}, \|\cdot\|)$  and  $L(\theta) \equiv \theta(x_0)$ . Also applies to derivatives.

**Example:** Let  $\theta(p, x)$  denote a demand function. For elasticity at a point  $(p_0, x_0)$ :

$$R(\gamma) = \{\theta \in W^{c\delta}(\mathcal{X}) : -p_0 \frac{\partial \theta(p_0, x_0)}{\partial p} \frac{1}{\theta(p_0, x_0)} = \gamma\} .$$

Now let  $(\mathcal{L}, \|\cdot\|_{\mathcal{L}}) = (\mathbf{R}, \|\cdot\|)$  and  $L(\theta) = -p_0 \frac{\partial \theta(p_0, x_0)}{\partial p} - \gamma \theta(p_0, x_0)$  and set:

$$R = \{\theta \in W^{c\delta}(\mathcal{X}) : L(\theta) = 0\} .$$

# Specification Testing

Let  $\mathcal{X}$  be compact,  $\{\psi_k\}_{k=1}^K \in W^{c\delta}(\mathcal{X})$  and define the parametric family:

$$\mathcal{P} \equiv \left\{ \theta \in W^{c\delta}(\mathcal{X}) : \theta(x) = \sum_{k=1}^K \beta_k \psi_k(x) \right\} .$$

Suppose we wish to test whether  $\Theta_0$  intersects with the parametric model,

$$H_0 : \Theta_0 \cap \mathcal{P} \neq \emptyset \qquad H_1 : \Theta_0 \cap \mathcal{P} = \emptyset .$$

Let  $(\mathcal{L}, \|\cdot\|_{\mathcal{L}}) = (L^2(\mathcal{X}), \|\cdot\|_{\mathcal{L}})$  and  $P_{\mathcal{P}}(\theta)$  be the projection of  $\theta \in L^2(\mathcal{X})$  onto  $\mathcal{P}$

$$\Theta_0 \cap \mathcal{P} = \Theta_0 \cap R \qquad R = \{ \theta \in W^{c\delta}(\mathcal{X}) : L(\theta) = 0 \} \qquad L(\theta) = P_{\mathcal{P}}(\theta) - \theta .$$

**Note:** Key property is  $\mathcal{P}$  be a vector subspace. Also for semiparametric models.

# Homogeneity

Suppose we wish to test for homogeneous production functions of degree  $\alpha$ .

$$\mathcal{P} \equiv \{\theta \in W^{c\delta}(\mathcal{X}) : \theta(\lambda k, \lambda l) = \lambda^\alpha \theta(k, l)\} .$$

To characterize homogeneity as a linear restriction, use Euler's Theorem:

$$\theta(\lambda k, \lambda l) = \lambda^\alpha \theta(k, l) \Leftrightarrow k \frac{\partial \theta(k, l)}{\partial k} + l \frac{\partial \theta(k, l)}{\partial l} = \alpha \theta(k, l) .$$

Let  $(\mathcal{L}, \|\cdot\|_{\mathcal{L}}) = (L^\infty(\mathcal{X}), \|\cdot\|_\infty)$  and  $L(\theta) = k \frac{\partial \theta(k, l)}{\partial k} + l \frac{\partial \theta(k, l)}{\partial l} - \alpha \theta(k, l)$  to obtain

$$\Theta_0 \cap \mathcal{P} = \Theta_0 \cap R \quad R = \{\theta \in W^{c\delta}(\mathcal{X}) : L(\theta) = 0\} .$$

and test whether the identified set  $\Theta_0$  contains homogenous functions.



Testing

Statistic

Bootstrap

Simulations

# Test Statistic

# Testing Outline

---

Since  $\Theta_0 \subseteq \Theta$ , we can rephrase the null hypothesis  $H_0 : \Theta_0 \cap R \neq \emptyset$  as:

Is there a  $\theta \in \Theta \cap R$  such that  $E[Y - \theta(X)|Z] = 0$ ?

**Goal:** Use this observation for a simple characterization of the null hypothesis.

## Strategy

- Suppose you had a **positive** functional  $F : \Theta \rightarrow \mathbf{R}$  such that:

$$F(\theta) = 0 \text{ iff } \theta \in \Theta_0 .$$

- If  $F$  is continuous under  $\|\cdot\|_{c\delta}$  and  $R$  is closed under  $\|\cdot\|_{c\delta}$ , then:

$$\Theta_0 \cap R \neq \emptyset \text{ iff } \min_{\theta \in \Theta \cap R} F(\theta) = 0 .$$

... **because**  $\Theta$  is compact under  $\|\cdot\|_{c\delta}$ .

# Conditional to Unconditional

## Revealing Functions

- Let  $\mathcal{Z}$  be the support of  $Z$ , let  $T \subset \mathbf{R}^{d_t}$  and  $w : T \times \mathcal{Z} \rightarrow \mathbf{R}$  be such that:

$$E[V|Z] = 0 \quad \text{if and only if} \quad E[Vw(t, Z)] = 0 \quad \forall t \in T \quad (GCR)$$

- **Examples:** Bierens (1990), Stinchcombe & White (1998).

**Lemma:** Under regularity conditions, it follows that if  $GCR$  holds:

$$\theta \in \Theta_0 \quad \text{iff} \quad \max_{t \in T} (E[(Y - \theta(X))w(t, Z)])^2 = 0 .$$

Moreover, exploiting compactness and continuity we also get:

$$\Theta_0 \cap R \neq \emptyset \quad \text{iff} \quad \min_{\theta \in \Theta \cap R} \max_{t \in T} (E[(Y - \theta(X))w(t, Z)])^2 = 0 .$$

# Test Statistic

$$I_n(R) \equiv \min_{\theta \in \Theta_n \cap R} \max_{t \in T_n} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta(X_i)) w(t, Z_i) \right)^2$$

## Sieve Details

- $T_n$  is a grid for  $T$ . The whole set  $T$  may be employed as well.
- For the sieve of  $\Theta \cap R$  we consider:

$$\Theta_n \cap R \equiv \{ \theta \in W^s(\mathcal{X}) : \theta(x) = p^{k_n}(x)h \text{ for } h \in \mathbf{R}^{k_n}, L(\theta) = l, \|\theta\|_s \leq B \} .$$

where  $p^{k_n}(x) = (p_1(x), \dots, p_{k_n}(x))'$  and  $p_i \in W^s(\mathcal{X})$  for all  $i$ .

- Constraints  $L(\theta) = l$  is **linear** in  $h$  and  $\|\theta\|^2 \leq B^2$  **quadratic** in  $h$ .

# Local Parameter Space

- For each  $\theta_0 \in \Theta_0 \cap R$ , let  $\Pi_n \theta_0$  be its projection onto  $\Theta_n \cap R$  (under  $\|\cdot\|_{L^2}$ ).

$$\underbrace{\theta_n(x)}_{\text{in } R} \equiv \underbrace{\Pi_n \theta_0(x)}_{\text{in } R} + p^{k'_n}(x) \frac{h}{\sqrt{n}} .$$

Since we must have  $L(p^{k'_n} h) = 0$ , the local values of  $h$  are contained in the set

$$\mathcal{H}_{k_n} \equiv \{h \in \mathbf{R}^{k_n} : L(p^{k'_n} h) = 0\} .$$

- Distribution depends on **effect of local parameters** on criterion function. Let,

$$V_{k_n}(T) \equiv \{v : T \rightarrow \mathbf{R} \text{ s.t. } v(t) = E[w(t, Z)p^{k'_n}(X)h], h \in \mathcal{H}_{k_n}\}$$

Define the function space  $V_\infty(T)$  the **closure** of  $\bigcup V_{k_n}(T)$  under  $\|\cdot\|_\infty$ .

# Some Intuition

$$\begin{aligned}
 & \min_{\Theta_n \cap R} \max_{T_n} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta_n(X_i)) w(t, Z_i) \right)^2 \\
 & \approx \min_{\Theta_n \cap R} \max_{T_n} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta_0(X_i)) w(t, Z_i) + \frac{1}{\sqrt{n}} \sum_{i=1}^n (\Pi_n \theta_0(X_i) - \theta_n(X_i)) w(t, Z_i) \right)^2 \\
 & \approx \min_{h \in \mathcal{H}_{k_n}} \max_{T_n} \left( \frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta_0(X_i)) w(t, Z_i) + \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{p^{k'_n}(X_i) h}{\sqrt{n}} w(t, Z_i) \right)^2 \\
 & \approx \min_{h \in \mathcal{H}_{k_n}} \max_{T_n} \left( \underbrace{\frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta_0(X_i)) w(t, Z_i)}_{\text{Gaussian Process}} + \underbrace{\frac{E[w(t, Z_i) p^{k'_n}(X_i) h]}{\sqrt{n}}}_{\text{in } V_{k_n}(T)} \right)^2
 \end{aligned}$$

# Asymptotic Distribution

**Theorem:** Under appropriate regularity conditions, if  $\Theta_0 \cap R \neq \emptyset$ , then:

$$I_n(R) \xrightarrow{L} \inf_{\theta_0 \in \Theta_0 \cap R} \inf_{v \in V_\infty(T)} \|G(t, \theta_0) - v(t)\|_\infty^2$$

where  $G(t, \theta_0)$  is a tight Gaussian process on  $L^\infty(T \times \Theta_0)$ . If  $\Theta_0 \cap R = \emptyset$ , then:

$$n^{-1} I_n(R) \xrightarrow{a.s.} \min_{\theta \in \Theta \cap R} \|E[(Y - \theta(X))w(t, Z)]\|_\infty^2$$

.

## Comments

- Statistic has a proper limit distribution under the null hypothesis.
- Statistic diverges to infinity under the alternative hypothesis.

# Alternative Result

---

**Remark:** If  $c_{1-\alpha}$  is the  $1 - \alpha$  quantile of  $\inf_{\Theta_0 \cap R} \|G(t, \theta_0)\|_\infty^2$  ...

... Then it is possible to show that under the null hypothesis:

$$\liminf_{n \rightarrow \infty} P(I_n(R) \geq c_{1-\alpha}) \geq 1 - \alpha .$$

... While under the alternative hypothesis we have:

$$\lim_{n \rightarrow \infty} P(I_n(R) \geq c_{1-\alpha}) = 1 .$$

## Comments

- Only requires that  $R$  be closed under  $\|\cdot\|_{c\delta}$ .
- Potentially conservative.



Testing

---

Statistic

---

**Bootstrap**

Simulations

---

# Bootstrap Procedure

# The Unknowns

---

Limiting distribution under the null hypothesis:

$$I_n(R) \xrightarrow{L} \inf_{\theta_0 \in \Theta_0 \cap R} \inf_{v \in V_\infty(T)} \|G(t, \theta_0) - v(t)\|_\infty^2 .$$

## Three Unknowns

- Distribution of the Gaussian process  $G(t, \theta_0)$ .
- Identified set  $\Theta_0 \cap R$ .
- The function space  $V_\infty(T)$ .

# Estimating $V_\infty(T)$

Recall that  $V_\infty(T)$  is the closure of  $\bigcup V_{k_n}(T)$  under  $\|\cdot\|_\infty$ , where:

$$V_{k_n}(T) \equiv \{v : T \rightarrow \mathbf{R} : \text{s.t. } v(t) = E[w(t, Z)p^{k'_n}(X)h], L(p^{k'_n}h) = 0 \}.$$

For some  $b_n \nearrow \infty$  and  $B_n \nearrow \infty$ , define the sample analogue:

$$\hat{V}_{b_n}(T) \equiv \left\{ v : T \rightarrow \mathbf{R} : \text{s.t. } v(t) = \frac{1}{n} \sum_{i=1}^n w(t, Z_i)p^{b'_n}(X_i)h, L(p^{b'_n}h) = 0, \|h\| \leq B_n \right\}.$$

## Comments

- $b_n$  plays role of  $k_n$  but they need not be equal.
- The norm bound  $B_n$  is imposed to obtain a uniform law of large numbers.

# Estimating $G(t, \theta_0)$

Recall that the Gaussian process  $G(t, \theta_0)$  on  $L^\infty(T \times \Theta_0)$  is the limit of:

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_i - \theta_0(X_i))w(t, Z_i) \xrightarrow{L} G(t, \theta_0) .$$

For  $(Y_i^*, X_i^*, Z_i^*)$  distributed according to the empirical distribution, we define:

$$G_n^*(t, \theta) \equiv \frac{1}{\sqrt{n}} \sum_{i=1}^n \{(Y_i^* - \theta(X_i^*))w(t, Z_i^*) - E^*[(Y_i - \theta(X_i))w(t, Z_i)] .\}$$

## Problem

- $G_n^*(t, \theta)$  is properly centered for all  $(t, \theta) \in T \times \Theta$ .
- $G_n^*(t, \theta)$  convergence is in  $L^\infty(T \times \Theta)$  not  $L^\infty(T \times \Theta_0)$ .
- Need to evaluate restriction of  $G_n^*(t, \theta)$  to proper domain.

# Estimating $\Theta_0 \cap R$

**Goal:** Use penalty function to evaluate  $G_n^*(t, \theta)$  on proper set. Define:

$$P_n^*(t, \theta) \equiv \left( \frac{1}{n} \sum_{i=1}^n (Y_i - \theta(X_i)) w(t, Z_i) \right)^2$$

## Indicator for Identified Set

If  $\lambda_n \nearrow \infty$  at an appropriate rate, then the penalty function:

$$\lambda_n \max_{t \in T} P_n^*(t, \theta)$$

... converges a.s. to zero for all  $\theta \in \Theta_0$  ... but diverges a.s. to  $+\infty$  for all  $\theta \notin \Theta_0$ .

# Consistency

$$I_n^*(R) \equiv \inf_{\theta \in \Theta_n \cap R} \inf_{v \in \hat{V}_{b_n}(T)} \max_{t \in T_n} \{(G_n^*(t, \theta) - v(t))^2 + \lambda_n P_n^*(t, \theta)\}$$

**Theorem** Under appropriate regularity conditions, if  $\Theta_0 \cap R \neq \emptyset$ , then:

$$I_n^*(R) \xrightarrow{L^*} \inf_{\theta_0 \in \Theta_0 \cap R} \inf_{v \in V_\infty(T)} \|G(t, \theta_0) - v(t)\|_\infty^2 \quad a.s.$$

On the other hand, if  $\Theta_0 \cap R = \emptyset$  then we obtain:

$$\lambda_n^{-1} I_n^*(R) \xrightarrow{p^*} \min_{\theta \in \Theta \cap R} \|E[(Y - \theta(X))w(t, Z)]\|_\infty^2 \quad a.s.$$

**Note:** Under the null, bootstrap equivalent to plug-in estimator for  $\hat{\Theta}_0$ .

# Inference

---

$$\hat{c}_{1-\alpha} \equiv \inf\{u : P^*(I_n^*(R) \leq u) \geq 1 - \alpha\}$$

**Corollary** Under  $H_0$ , if limit distribution of  $I_n(R)$  is continuous, strictly increasing,

$$\lim_{n \rightarrow \infty} P(I_n(R) \leq \hat{c}_{1-\alpha}) = 1 - \alpha .$$

On the other hand, if  $\Theta_0 \cap R = \emptyset$ , then we have:

$$\lim_{n \rightarrow \infty} P(I_n(R) > \hat{c}_{1-\alpha}) = 1 .$$

**Note:** Consistency is due to  $I_n^*(R)$  diverging to infinity at slower rate than  $I_n(R)$ .

Testing

Statistic

Bootstrap

Simulations

# Monte Carlo



# Monte Carlo

---

## Distribution Design

- $(X, Z, \epsilon)$  transformed from multivariate normal  $(X^*, Z^*, \epsilon^*)$ .
- $\rho(X^*, Z^*) = 0.5$  and  $\rho(X^*, \epsilon^*) = 0.3$ ,  $(X, Z)$  have compact support.
- True model:  $Y = 2 \sin(X\pi) + \epsilon$

## Implementation Details

- B-Splines used for sieve  $\Theta_n$ .
- Weight function  $w(t, z) = \phi((t_1 - z)/t_2)$ , where  $\phi(u)$  is normal pdf.
- 500 replications, sample size of 500.

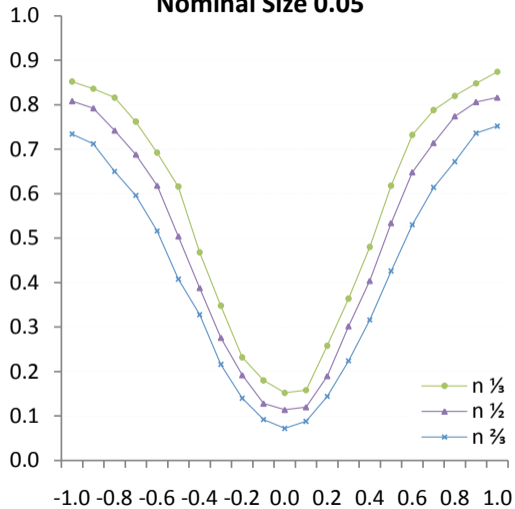
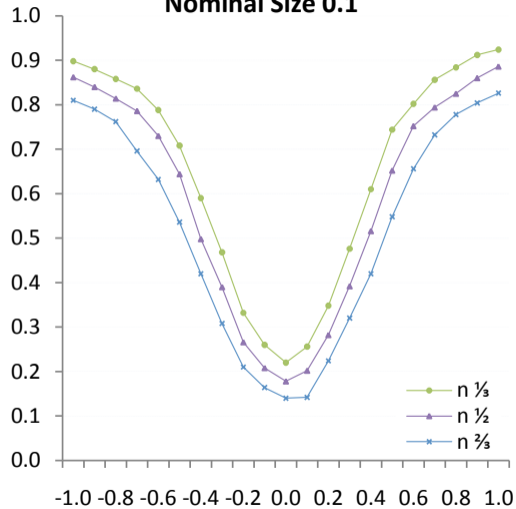
# Empirical Size

**Null hypothesis:** Does  $\theta_0(0) = 0$ ?

$\alpha/\lambda_n$	$\lambda_n = 0$	$\lambda_n = n^{\frac{1}{3}}$	$\lambda_n = n^{\frac{1}{2}}$	$\lambda_n = n^{\frac{2}{3}}$
$\alpha = 0.1$	0.508	0.220	0.178	0.140
$\alpha = 0.05$	0.378	0.152	0.114	0.072
$\alpha = 0.01$	0.198	0.050	0.028	0.014

## Comments

- $\lambda_n = 0$  not warranted by theory. Should over-reject.
- $(n^{\frac{1}{3}}, n^{\frac{1}{2}}, n^{\frac{2}{3}}) \approx (7.9, 22.4, 63) \dots$  broad range for choices.
- $n^{\frac{1}{3}}$  seems to be too small, controls size poorly.

**Nominal Size 0.05****Nominal Size 0.1**

# Final Remarks

---

## Partial Identification

- Smoothness restriction aid in identification but do not guarantee it.
- Straightforward to construct examples where identification fails.

## Methods for Inference

- Robust to partial identification.
- Identifiable functionals through test inversion.
- Bootstrap procedure for obtaining critical values.