

# Extensive Game with Imperfect Information

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# Extensive Game with Imperfect Information

- We consider dynamic games where past “moves” (by players or nature) are imperfectly observed.

## Example 1: Observational Learning

- $n$  players are lined up.
- Each player has two options: buy a new iPad (B) or do not buy (N).
- The quality of new iPad may be high (H) with probability  $p \in (0, 1)$  or low (L) with probability  $1 - p$ .  $p$  is a common prior. The quality is common to all players.
- Player  $i$  observes a private signal  $s_i \in \{h, l\}$ , which is correct with probability  $q \in (0, 1)$ , and the choice of the preceding players:  $(a_1, \dots, a_{i-1})$ .
- The net payoff from purchasing an iPad is 1 if the quality is good and  $-1$  if the quality is bad.

## Example 2: Cheap Talk/Information Transmission

- Two players: Manager(M) and Analyst(A). M likes to figure out what is the right size of investment for a new project. A has an access to this information.
- A learns the right size, which is either “small”, “medium”, “large”. He conveys this information to M (but he can lie). Then M chooses the size of the investment.
- A prefers a slightly excessive level of investment: he prefers “medium” when he learns “small”, prefers “large” when he learns “medium” or “large”.

## Extensive Game with Imperfect Information

- **Extensive game** is an extension of extensive game with perfect information.

- ▶ a finite set  $N$
- ▶ a set of finite or infinite sequences  $H$  such that
  - ★  $\emptyset \in H$
  - ★  $(a^1, \dots, a^k) \in H \rightarrow (a^1, \dots, a^\ell) \in H$  for any  $\ell < k$
  - ★  $(a^1, \dots) \in H$  if  $(a^1, \dots, a^k) \in H$  for  $k = 1, 2, \dots$

with  $Z \subset H$  defined by  $(a^1, \dots, a^k) \in Z \Leftrightarrow \nexists a^{k+1}, (a^1, \dots, a^{k+1}) \in H$ .

- ▶ a function  $P : H/Z \rightarrow N \cup \{c\}$ .
- ▶ a function  $f_c$  that assigns a probability distribution  $f_c(h) \in \Delta(A(h))$  for each  $h$  such that  $P(h) = c$ .
- ▶ a partition  $\mathcal{I}_i$  of  $H_i = \{h \in H | P(h) = i\}$  for each  $i \in N$  such that  $A(h) = A(h')$  for any  $h, h' \in I_i \in \mathcal{I}_i$  and any  $i \in N$ .
- ▶ a function  $V_i : Z \rightarrow \Re$  for  $i \in N$ .

- $N, H, Z, P, f_c$  and  $V_i$  are the same as before.
- What is new is  $\mathcal{I}_i$ : a collection of **information sets** for each  $i \in N$ .  
Each  $I_i \in \mathcal{I}_i$  is player  $i$ 's information set: the set of histories that player  $i$  cannot distinguish.
- “ $A(h) = A(h')$  for any  $h, h' \in I_i \dots$ ” reflects this informational restriction.
- We denote the set of actions available at  $I_i$  by  $A(I_i)$ .

# Strategies

- Three kind of strategies:
  - ▶ Player  $i$ 's pure strategy for extensive game  $(N, H, P, f_c, (\mathcal{I}_i), (V_i))$  is a mapping  $s_i$  that assigns an action in  $A(I_i)$  for each  $I_i \in \mathcal{I}_i$ . Let  $S_i$  be the set of player  $i$ 's strategies.
  - ▶ Player  $i$ 's mixed strategy is a probability distribution over pure strategies (an element in  $\Delta(S_i)$ ).
  - ▶ Player  $i$ 's behavior strategy is a mapping  $\sigma_i$  that assigns a probability measure on  $A(I_i)$  for each  $I_i \in \mathcal{I}_i$ . Let  $\Sigma_i$  be the set of player  $i$ 's behavior strategies.
- **Remark.** For mixed and behavior strategies, we assume that the set of actions is finite:  $A(h)$  is a finite set for any  $h \in H$ .

- Each profile of strategies determines an outcome  $O(s) \in Z$  or a distribution of outcomes  $\tilde{O}(\sigma) \in \Delta(Z)$ .
- Player  $i$ 's payoff given  $s$  and expected payoff given  $\sigma$  are  $V_i(O(s))$  and  $E[V_i(\tilde{O}(\sigma))]$ , which we denote by  $V_i(s)$  and  $V_i(\sigma)$  respectively.

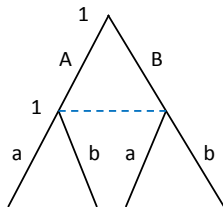
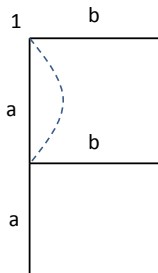


## Perfect Recall

- For any  $h \in H$ , let  $X_i(h)$  be the sequence of player  $i$ 's information sets along  $h$ .
- We almost always assume **perfect recall**:  $X_i(h) = X_i(h')$  for any  $h, h' \in I_i$  for any  $I_i \in \mathcal{I}_i$  for any  $i \in N$ .
- Without perfect recall, a player may forget what she knew (what she played etc.)

## Example

- Without perfect recall, mixed strategies and behavior strategies are not equivalent unlike in the case of perfect information.



- Two mixed or behavior strategies are **outcome equivalent** if they generate the same outcome distribution given any pure strategy of the other players.
- With perfect recall, we do not need to distinguish behavior strategies and mixed strategies in finite extensive games in the following sense.

## Theorem

- ▶ For any mixed strategy of finite extensive game, there exists an outcome equivalent behavioral strategy.
- ▶ For any behavior strategy of finite extensive game, there exists an outcome equivalent mixed strategy.

## Nash Equilibrium

- For any extensive game  $(N, H, P, f_c, (\mathcal{I}_i), (V_i))$ , there exists a strategic game  $(N, (S_i), (V_i))$ . So we can define Nash equilibrium for extensive game as usual.

### Nash Equilibrium

For extensive game  $(N, H, P, f_c, (\mathcal{I}_i), (V_i))$ , a profile of strategies  $s^*$  is a Nash equilibrium if

$$V_i(s^*) \geq V_i(s'_i, s^*_{-i})$$

for any  $s'_i \in S_i$  and any  $i \in N$ .

- Again our interest is to come up with a reasonable refinement of Nash equilibrium.